

# Modulation Domain Image Processing

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## Research Goals

- ① Develop a perfect reconstruction AM-FM image transform.
  - Develop a perfect reconstruction (PR) filterbank.
  - Develop a robust FM reconstruction algorithm.
- ② Design image processing filters in the modulation domain.
  - AM-based image processing.
  - FM-based image processing.

- ① A new modulation domain image filtering framework with two classes of perceptually motivated image filters.
- ② A true multi-orientation multi-scale PR filterbank.
- ③ An artifact-free AM-FM demodulation algorithm.
- ④ A perfect reconstruction FM algorithm.
- ⑤ Extensions of the xAMFM for image decomposition problems.

## Organization

- ① Part I: Theory
  - The AM-FM Image Model
  - The Multi-scale Multi-orientation PR Filterbank
  - The PR AM-FM Transform
- ② Part II: Modulation Domain Image Filtering
  - AM-based Image Filtering
  - FM-based Image Filtering
- ③ Part III: Extensions and Conclusions

## 1 Part I: Theory

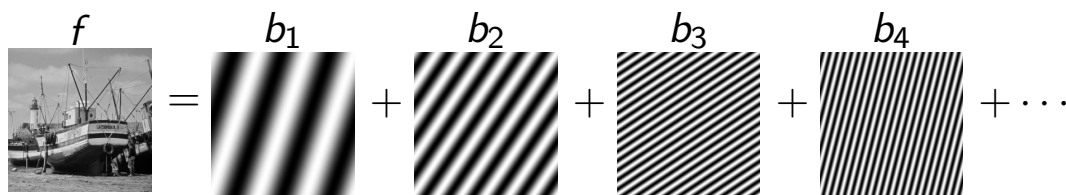
- The AM-FM Image Model
- The Multi-scale Multi-orientation PR Filterbank
- The PR AM-FM Transform

## 2 Part II: Modulation Domain Image Filtering

- AM-based Image Filtering
- FM-based Image Filtering

## 3 Part III: Extensions and Conclusions

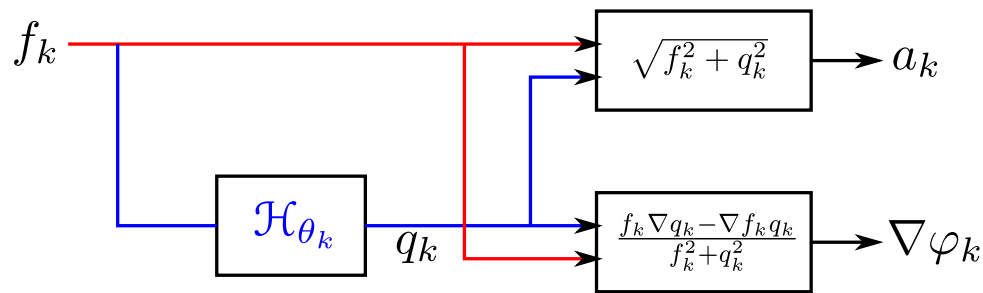
# AM-FM Image Model



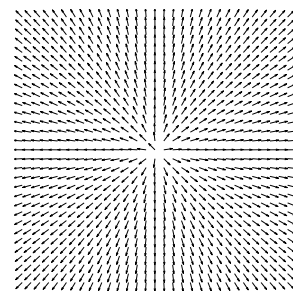
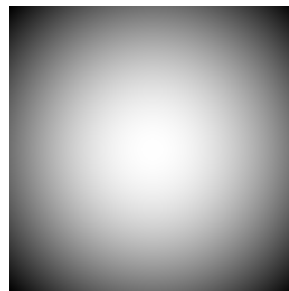
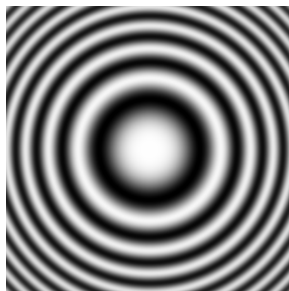
The AM-FM image model represents an image  $f(\mathbf{x})$  as

$$f(\mathbf{x}) = \sum_{k=1}^K f_k(\mathbf{x}) = \sum_{k=1}^K a_k(\mathbf{x}) \cos[\varphi_k(\mathbf{x})].$$

- $a_k(\mathbf{x})$ : amplitude modulation (AM)  $\rightarrow$  **local contrast**.
- $\nabla \varphi_k(\mathbf{x})$ : frequency modulation (FM)  $\rightarrow$  **local texture orientation and spacing**.



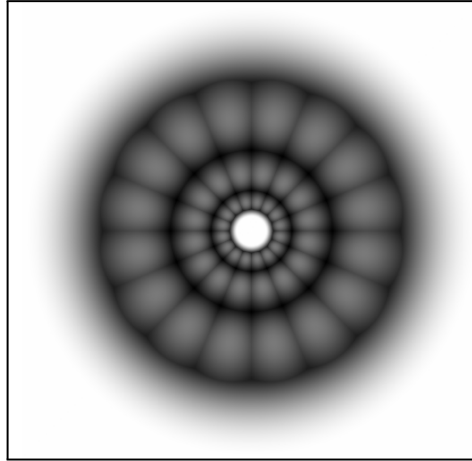
- $q_k = \mathcal{H}_{\theta_k}[f_k]$ .
- $a_k$  and  $\nabla \varphi_k$  are computed *exactly*.



## The Current State of AM-FM image processing

- Successfully used in many image processing applications such as image segmentation, content-based retrieval, fingerprint analysis, and target tracking.
- **Problems:** Most AM-FM applications are limited to analysis-only.
  - ① Approximation errors of demodulation algorithms.
  - ② Lack of perfect reconstruction algorithms.
- **Solution:**
  - ① A perfect reconstruction multi-component AM-FM transform.
  - ② A robust reconstruction algorithm that produces high quality perceptually motivated filtering results.





- Early 1990s by Freeman, Adelson, and Simoncelli.
- Multi-scale multi-orientation signal analysis.
- Used in many image processing applications.

## The Modified Steerable Pyramid: Cont.

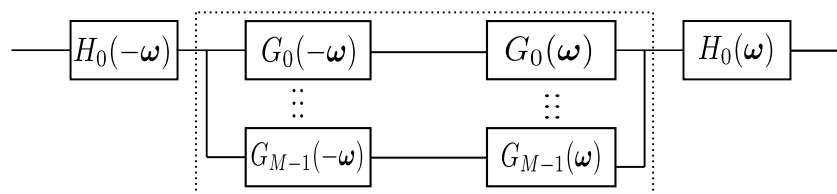
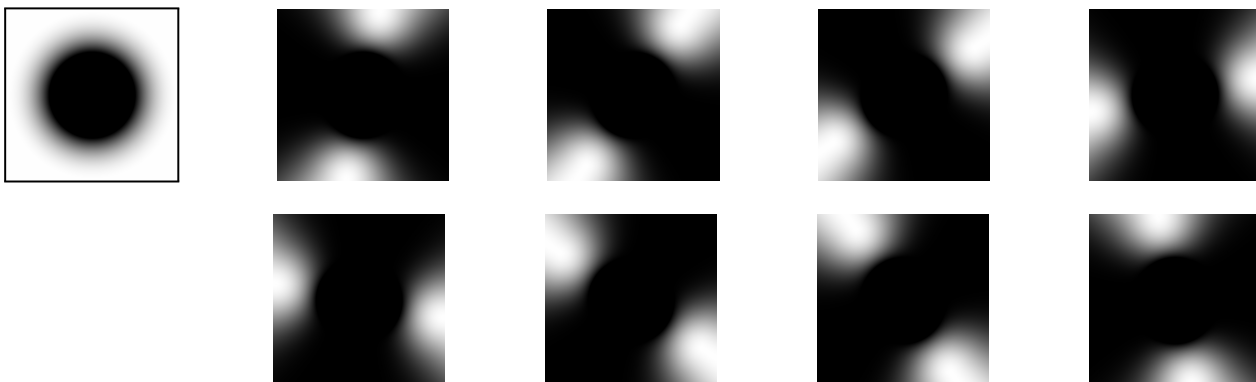


Figure: Hi-pass ring decomposition.



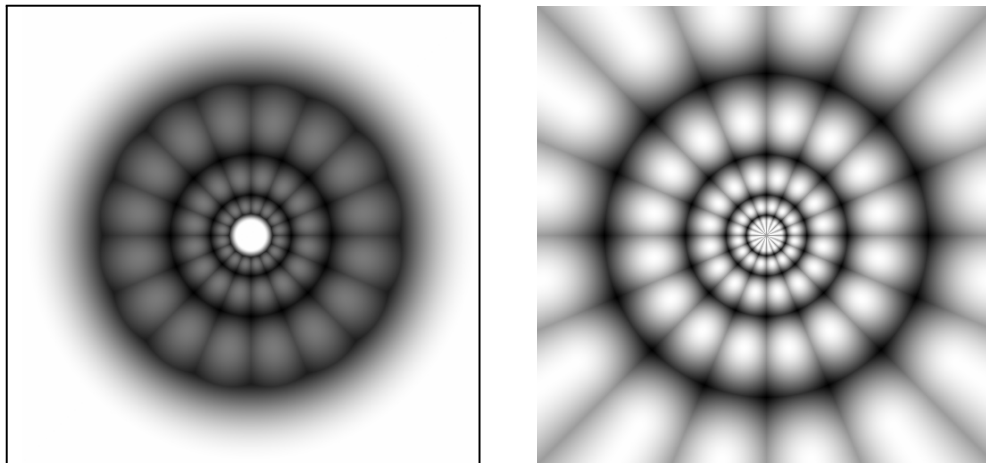


Figure: Original v.s. Modified steerable pyramid

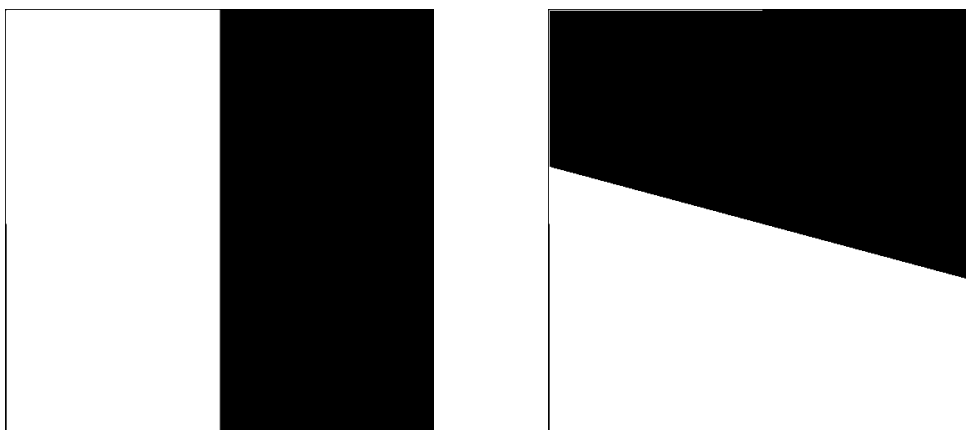
## Rotation of the partial Hilbert transform

$$\widehat{q}_{\mathbf{e}}(\boldsymbol{\omega}) = -j \text{sgn}(\boldsymbol{\omega}^T \mathbf{e}) \widehat{f}_k(\boldsymbol{\omega}).$$

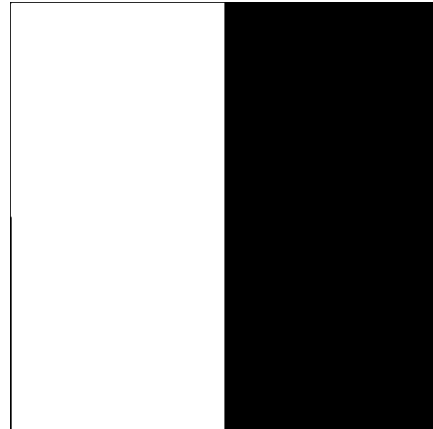
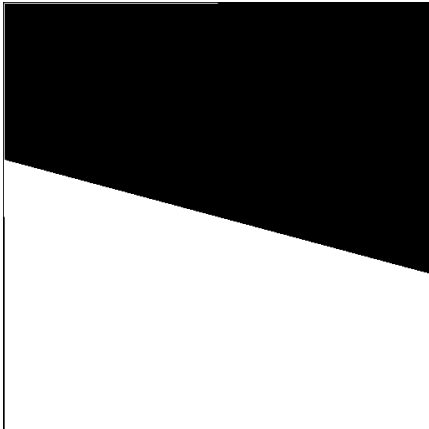
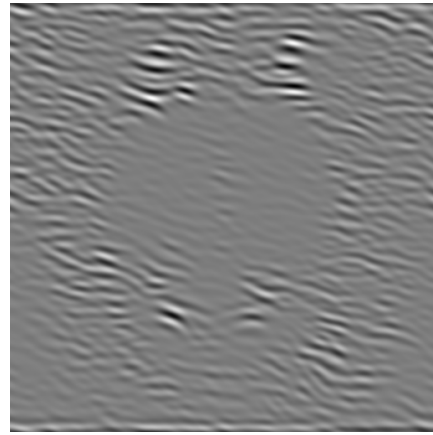
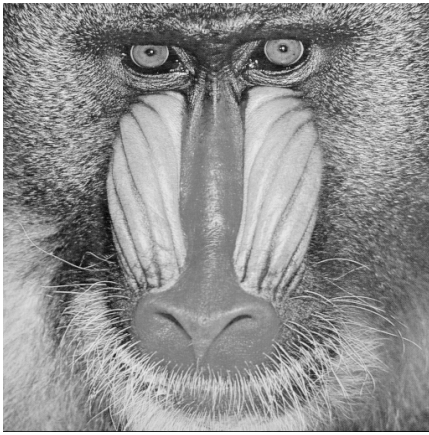
**Problem:** locations that have frequency support orthogonal to  $\mathbf{e}$

- rippling artifacts in the computed AM.
- distortion in the computed FM.

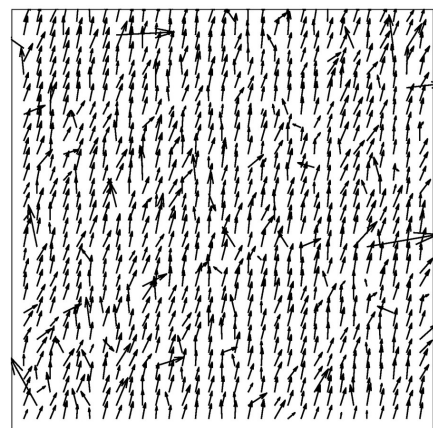
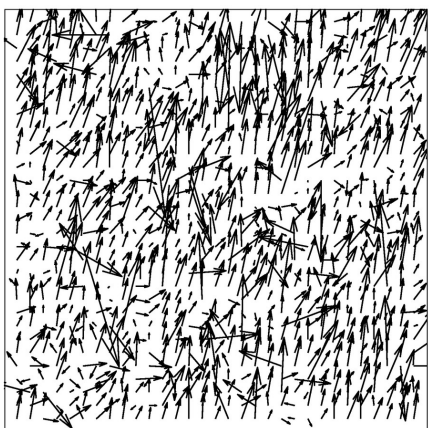
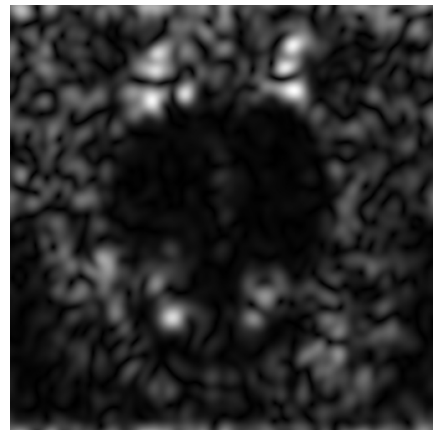
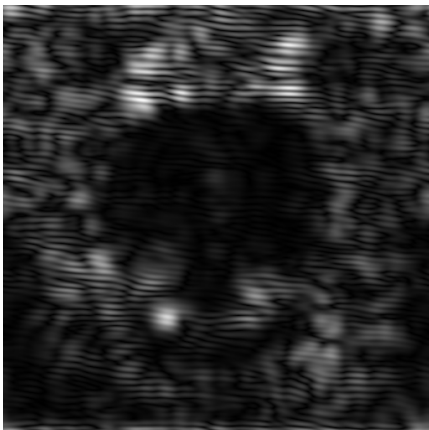
**Solution:** rotate the pHT's direction of action such that  $\mathbf{e}$  is orthogonal to the steerable pyramid filter center frequency.



# Rotation of the Partial Hilbert Transform



# Rotation of the Partial Hilbert Transform



Let  $f_k(m, n) = a_k(m, n) \cos[\varphi_k(m, n)]$ .

Let  $\nabla\varphi_k(m, n) = [U(m, n) \ V(m, n)]^T$  be the FM of  $f_k(m, n)$ .

Sivley and Havlicek proposed a spline-based FM reconstruction.

- Perfect FM reconstruction.
- Cubic tensor product spline.
- Smooth phase function  $\varphi_k(m, n)$ .

## Problems:

- 1 Reconstructed phase requires a priori knowledge of four pixels.
- 2 The phase scaling factor problem.
- 3 Unstable to small changes of  $U(m, n)$  and  $V(m, n)$ .
- 4 Changes in  $U(m, n)$  and  $V(m, n)$  are not effectively reflected in the reconstructed phase.

# AM-FM Reconstruction Algorithm: Cont.

Let  $f_k(m, n) = a_k(m, n) \cos[\varphi_k(m, n)]$ .

Let  $\psi(m, n)$  be the reconstructed phase function.

Solved using a least-squares approach

$$\mathcal{E}[\psi(m, n)] = \|\psi_m(m, n) - V(m, n)\|^2 + \|\psi_n(m, n) - U(m, n)\|^2.$$

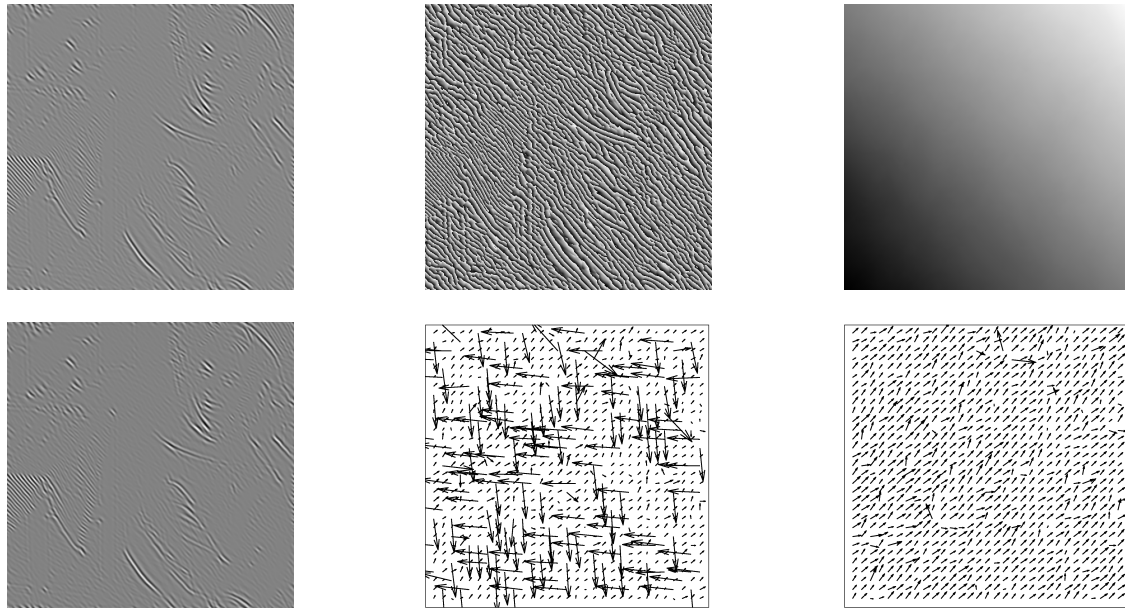
**Problem:**  $\cos[\psi(m, n)] \neq \cos[\varphi_k(m, n)]$ .

## Solution:

- $\varphi_k(m, n) = \psi(m, n) + \tau(m, n)$ .
- Recompute  $\nabla\varphi_k(m, n) = [U(m, n) \ V(m, n)]^T$ .

## Advantages:

- Reconstructed phase requires a priori knowledge of one pixel.
- Robust to changes in  $U(m, n)$  and  $V(m, n)$ .



## The PR AM-FM Transform.

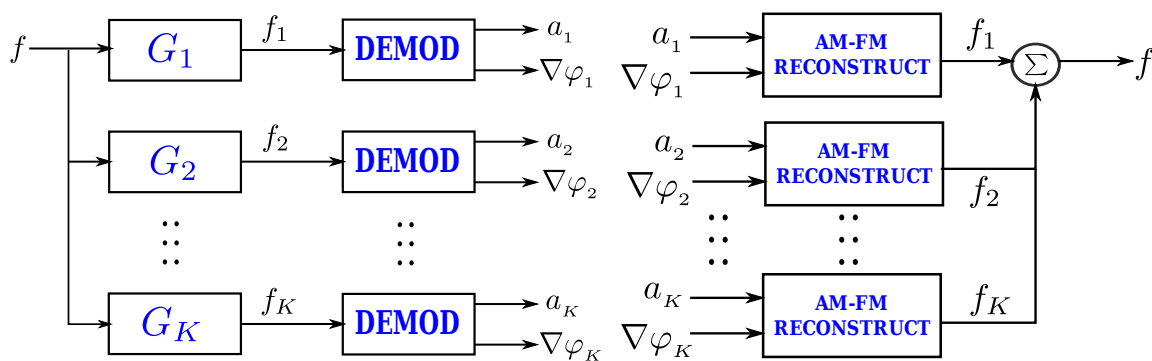


Figure: The xAMFM

Let  $f$  be the original image. Let  $g$  be the reconstructed image.

$$\text{MSE}(f, g) = \frac{\sum_{m=0}^{M-1} \sum_{n=0}^{N-1} [f(m, n) - g(m, n)]^2}{MN},$$

$$\text{PSNR}(f, g) = 10 \log_{10} \left( \frac{\max[f]}{\text{MSE}(f, g)} \right).$$

## xAMFM: Reconstruction Errors

**Table:** Reconstruction error of the xAMFM.

	Dimension	PSNR (dB)	MSE
Lena	512x512	80.903801	$4.874747 \times 10^{-04}$
Barbara	512x512	74.902187	$1.957273 \times 10^{-03}$
Boat	512x512	78.522112	$9.138380 \times 10^{-04}$
EinSlack	375x500	78.706215	$8.085571 \times 10^{-04}$
Fingerprint	512x512	74.680474	$2.213262 \times 10^{-03}$
Flintstones	512x512	73.169935	$3.133912 \times 10^{-03}$
House	256x256	84.772617	$1.903418 \times 10^{-04}$
kodim01	512x768	74.077160	$2.543105 \times 10^{-03}$
kodim05	512x768	73.993926	$2.592315 \times 10^{-03}$
kodim08	512x768	70.226141	$6.172573 \times 10^{-03}$
kodim17	768x512	78.422051	$9.351371 \times 10^{-04}$
kodim22	512x768	77.991403	$1.032619 \times 10^{-03}$
kodim23	512x768	79.323793	$7.598032 \times 10^{-04}$

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## AM-FM Image Filtering

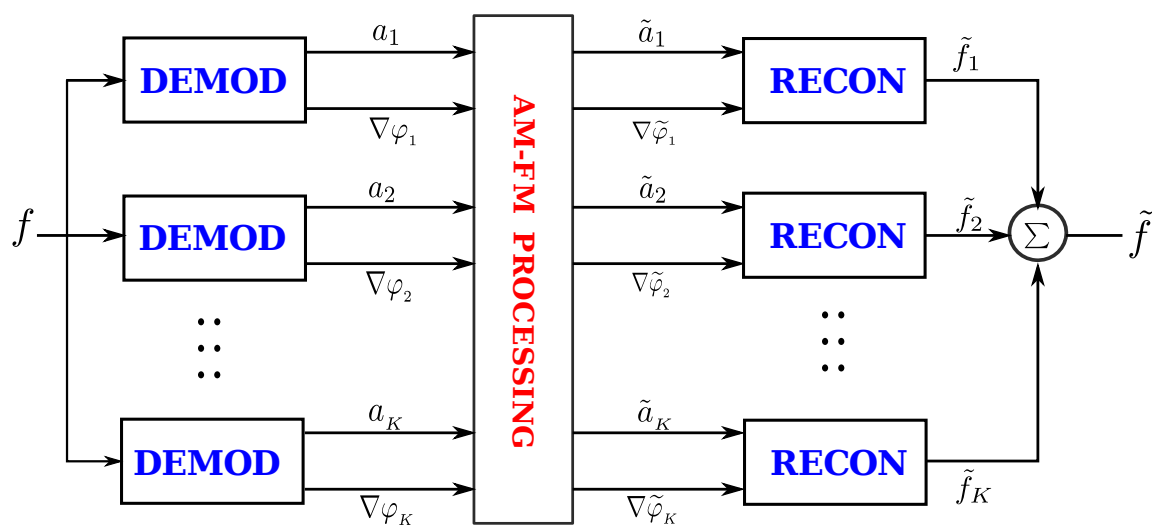


Figure: AM-FM Filtering



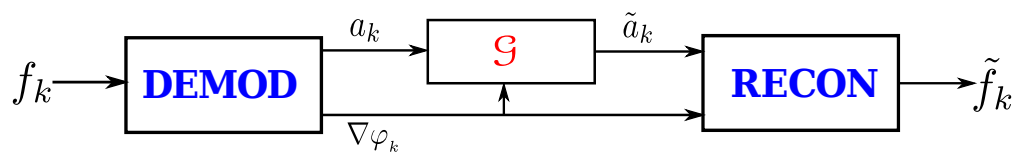


Figure: AM-based Image Filtering

- AM is filtered by filter  $\mathcal{G}$ .
- FM is unchanged.

## AM-based: Orientation Selective Attenuation

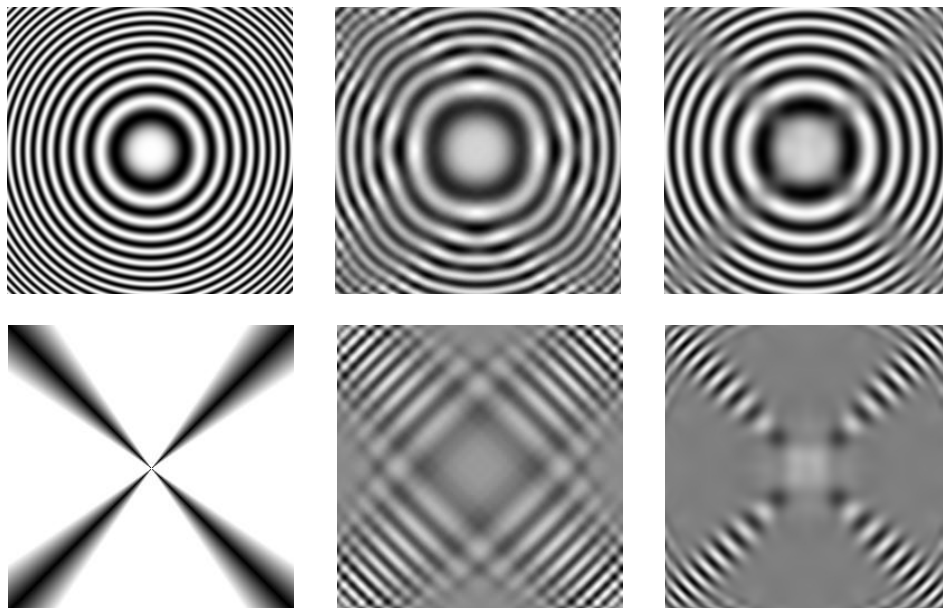


Figure: AM-based selective orientation attenuation.



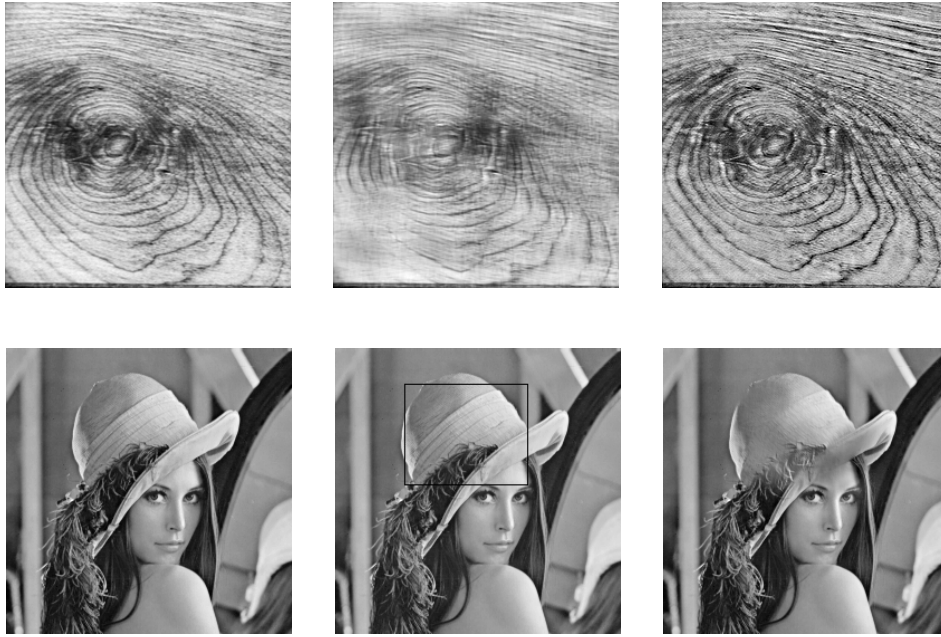


Figure: AM-based image enhancements.

## AM-based Image Filtering: Frequency Selective Filtering

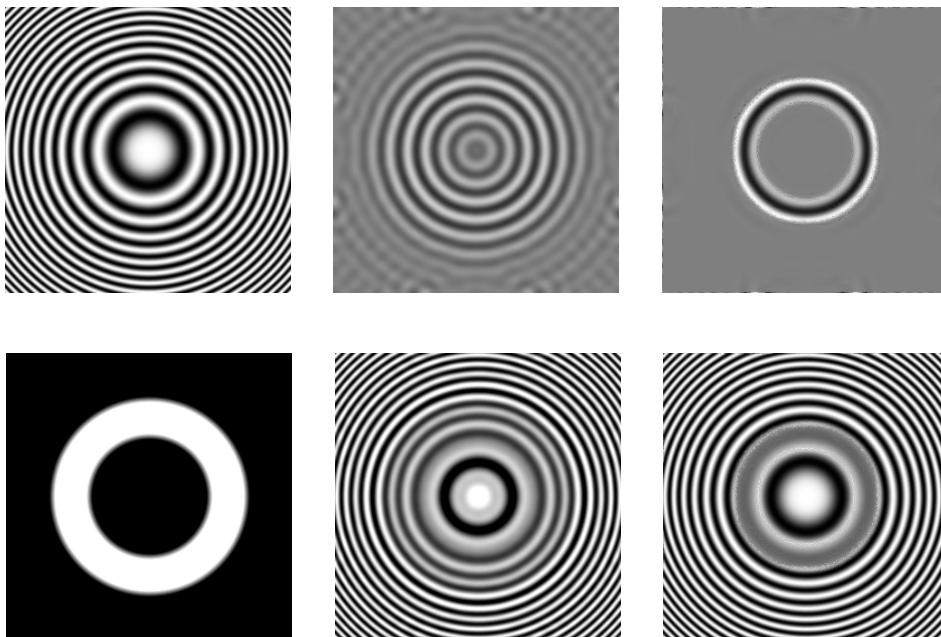


Figure: AM-based bandpass filter.

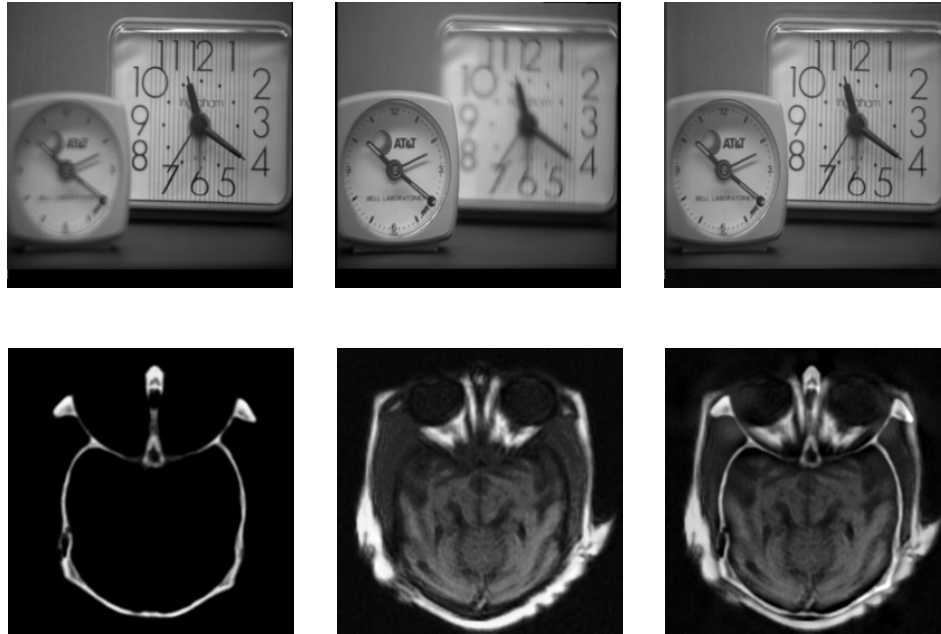


Figure: AM-FM image fusion.

## Image Fusion Examples

MI	Wavelet	LP	AM-based
clock	0.577370	<b>0.630707</b>	0.610730
tiffany	0.669841	0.64423	<b>0.671626</b>
lena	<b>0.747307</b>	0.72831	0.704051
medical	<b>0.413435</b>	0.365575	0.305687
navigation	<b>0.242832</b>	0.25451	0.239581

OEPL	Wavelet	LP	AM-based
clock	0.731238	<b>0.754339</b>	0.742081
tiffany	0.735087	<b>0.739462</b>	0.738636
lena	<b>0.741060</b>	0.739007	0.728825
medical	0.692751	<b>0.789651</b>	0.716454
navigation	0.613523	<b>0.697676</b>	0.640881

SSIM-based	Wavelet	LP	AM-based
clock	0.490198	<b>0.509316</b>	0.502113
tiffany	0.531843	<b>0.535119</b>	0.534410
lena	0.548370	<b>0.549710</b>	0.544959
medical	<b>0.301499</b>	0.279124	0.261661
navigation	0.198293	0.295320	<b>0.417149</b>

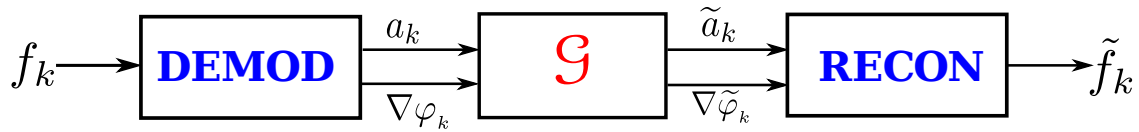


Figure: FM-based Image Filtering

- Both AM and FM functions are filtered.

## Generalized AM and FM functions

Let  $f_k(\mathbf{n}) = a_k(\mathbf{n}) \cos[\varphi_k(\mathbf{n})]$ .

- Recall that PR requires  $\varphi_k(\mathbf{n}) = \psi_k(\mathbf{n}) + \rho_k(\mathbf{n})$ .
- The congruency term  $\rho_k(\mathbf{n})$  is the source of artifacts for FM-based filtering.

**Solution:** move the congruency term  $\rho_k(\mathbf{n})$ .

- Generalized AM functions  $A_{1k}(\mathbf{n})$  and  $A_{2k}(\mathbf{n})$ .
- Generalized FM function  $\psi_k(\mathbf{n})$ .

$$\begin{aligned}
 f_k(\mathbf{n}) &= a_k(\mathbf{n}) \cos[\varphi_k(\mathbf{n})] = a_k(\mathbf{n}) \cos[\psi_k(\mathbf{n}) + \rho_k(\mathbf{n})] \\
 &= a_k(\mathbf{n}) \cos[\rho_k(\mathbf{n})] \cos[\psi_k(\mathbf{n})] - a_k(\mathbf{n}) \sin[\rho_k(\mathbf{n})] \sin[\psi_k(\mathbf{n})] \\
 &\equiv A_{1k}(\mathbf{n}) \cos[\psi_k(\mathbf{n})] + A_{2k}(\mathbf{n}) \sin[\psi_k(\mathbf{n})].
 \end{aligned}$$

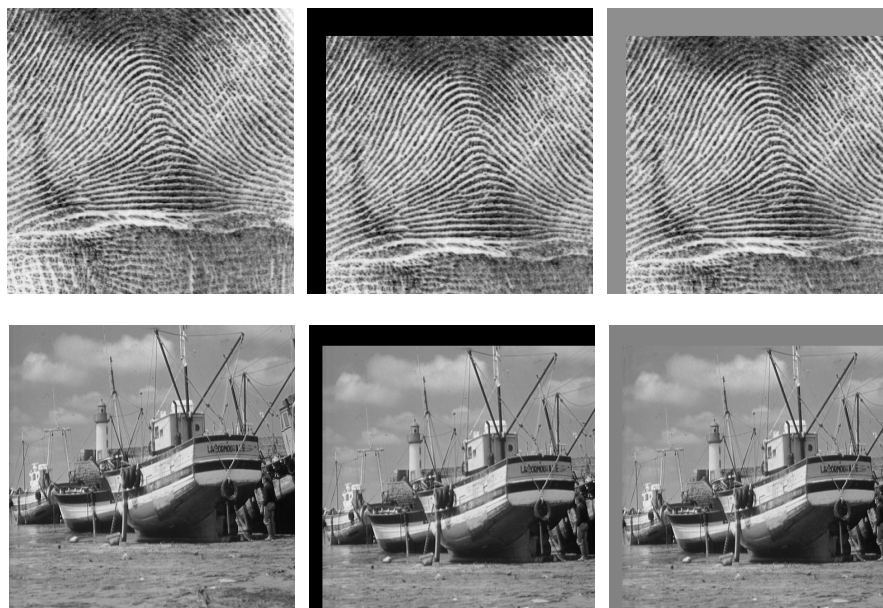


Figure: AM-FM image shift.  $\mathbf{u} = (34.70, 50.30)$  and  $\mathbf{u} = (24.50, 37.30)$ .

## Scaling

Let  $L \in \mathbb{R}$  be the scaling factor.

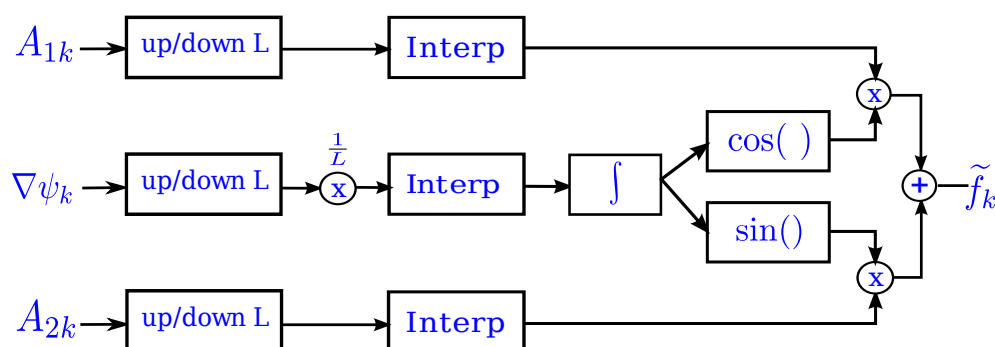


Figure: Block diagram of modulation domain image scaling.



Figure: AM-FM image zoom.

## FM-based: Image Scaling

Table: Comparison of the upsampling operation.

	PSNR (dB)		SSIM	
	Bicubic	AM-FM	Bicubic	AM-FM
Boat	33.488	<b>33.697</b>	0.765	<b>0.799</b>
Barbara	32.091	<b>32.179</b>	0.716	<b>0.728</b>
Lena	35.018	<b>35.214</b>	0.852	<b>0.862</b>
Fingerprint	30.362	<b>30.488</b>	0.864	<b>0.869</b>



Let

$$\mathcal{O}_\alpha = \begin{bmatrix} \cos(\alpha) & \sin(\alpha) \\ -\sin(\alpha) & \cos(\alpha) \end{bmatrix} \quad (1)$$

be the rotation matrix by an arbitrary angle  $\alpha$  and let  $\mathcal{R}_\alpha$  be the rotation operation by an angle  $\alpha$  acting on the pixel lattice.

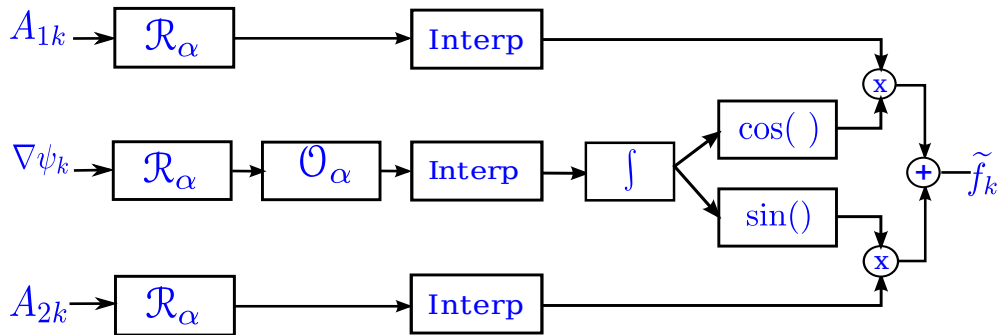


Figure: Block diagram of modulation domain image rotation.

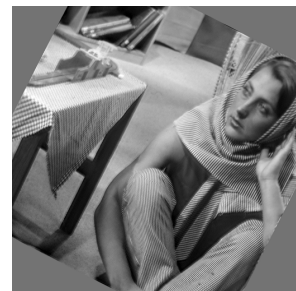
## Rotation: Examples



(a) Original.



(b) Spatial 27°.



(c) AM-FM 27°.



(d) Original.



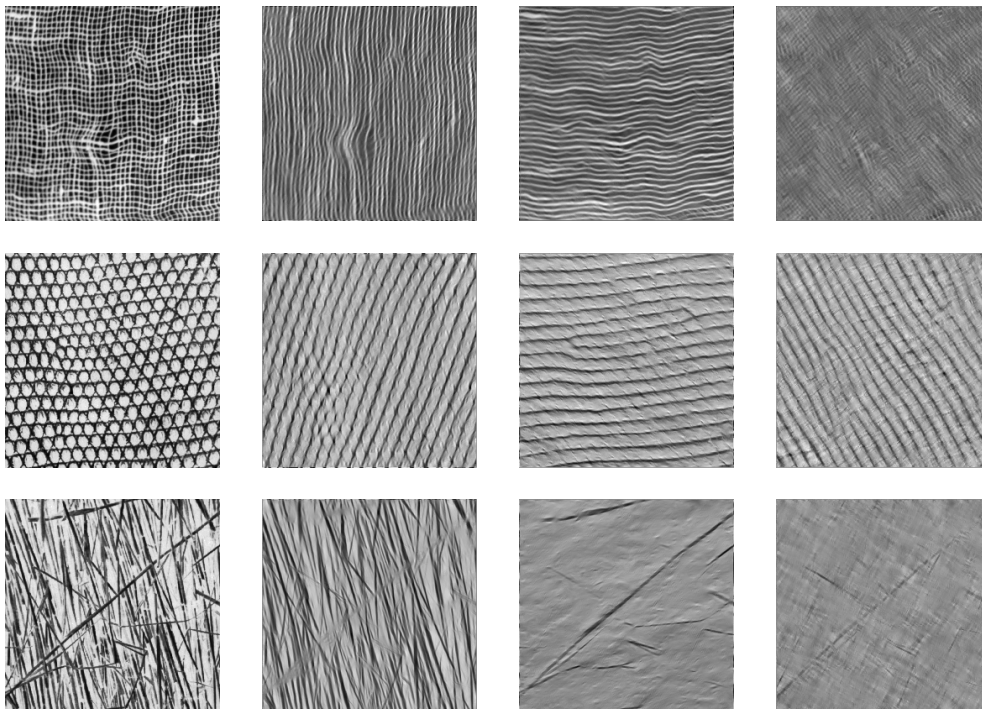
(e) Spatial 45°.

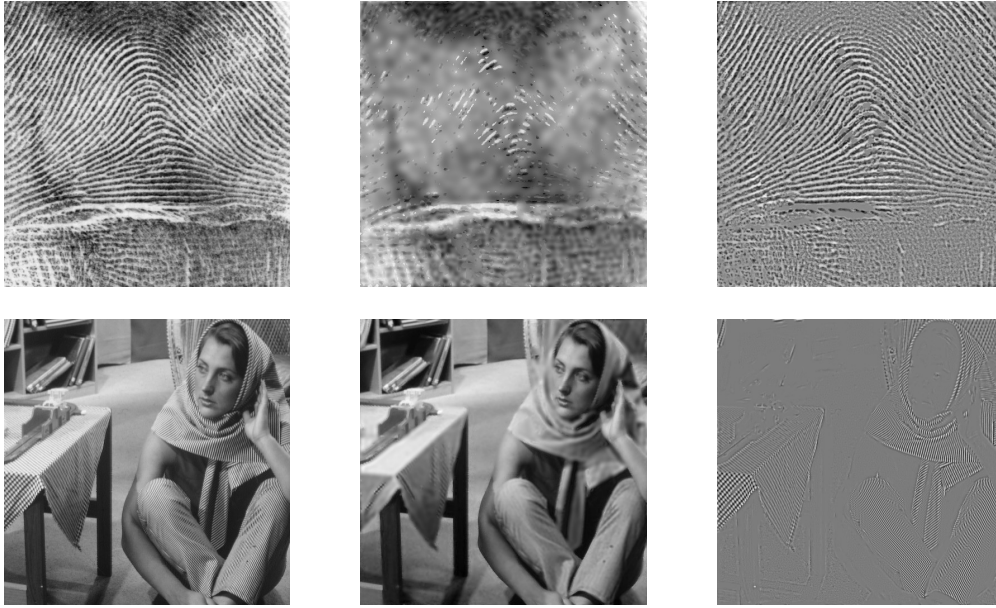


(f) AM-FM 45°.

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## Coherent Texture Decomposition





## Original Contributions

- 1 New modulation domain image filtering framework with two classes of perceptually motivated image filters.
- 2 A true multi-orientation multi-scale PR filterbank.
- 3 An artifact-free AM-FM demodulation algorithm.
- 4 A perfect reconstruction FM algorithm.
- 5 Extensions of the xAMFM for image decomposition problems.



- New field of perceptually motivated image filtering.
- Foundation for general/sophisticated filters.
- Effect of noise.
- Image and video quality assessment.
- The challenging data driven decomposition.

## Conclusion

- Developed the PR AM-FM transform (xAMFM).
- Designed perceptually motivated modulation domain filters.
- Used the xAMFM in image processing applications.

Thank you!